## An Introduction to R

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## 1 First steps

We try some first inputs in the command line of R. For the first time, type 17 + 2 and press enter and you will see the following:

> 17 + 2 [1] 19

The output [1] 19 says that this is the first output, and the output is 19. If you do it again you will get [2] 19 and so on. In the following the sign > will show you what to type and the following line(s) is the output.

R takes automatically control of brackets:

> sqrt (pi\*x ^2 + 5)

The + sign shows that **R** expects you to finish the line. It appears by pressing enter after 2.

Storing data in variables can be done as follows:

> x <- 119 + 2

There is no output. But now 121 is stored in x and you can bring it up as follows:

> x [1] 121

In the following we leave aside the outputs from R and just give the commands. Typically we use a table for assessing R commands as follows:

Objects in R	
objects()	Gives you a list of currently used storage variables, or ob- jects. For example [1] "a" "b" "x"
objects	As this is a function, calling it without brackets give you the definition of the function. This is very helpful in accessing what happens on calling functions, in particular the ones which you write yourself.
rm(x, y)	Removes these objects from the workspace.

R has a powerful help. You can invoke it by

> help( mean)

or get a short cut by

> ? mean

One of the most often used function is c. It concatenates objects:

> c(1,2,5,78) [1] 1 2 5 78

#### 1.1.1 More complicated things

Next we experiment with sequences.

> 1:10

creates a sequence from 1 to 10. There are a number of powerful way to do this. Compute the mean of the first 100 integers.

> x <- seq(from=-1, to = 8, by = 0.1) #This is a comment > y <-  $x^2$  #Store in y And bring it to the screen:

> plot(x,y,type = "l",main="The function x^2", xlab="x", ylab="y")

If you want to add a further line to an existing plot, you use lines:

#### > lines(x,x^3,type = "l",col="blue")

**Exercise 1.** Now get help on the command plot, try different functions, like square root and logarithm and so on. Some examples are listed below

The function plot		
plot(sin)	Functions are objects which have a direct plotting method. You can find out about all such objects with methods(plot)	
<pre>plot(sin(seq(-pi,pi,by=0.01)),     type="l",col=8,lwd=4,bty="l")</pre>	<pre>type="1" gives lines instead of just circles, col="red" gives the color, lwd: line width, bty="1" specifies the frame: "o" is stan- dard, "n" is none. For legends see below.</pre>	

#### 1 First steps

Interactive Features		
<pre>x &lt;- 1:10 y &lt;- x^2 plot(x,y) identify(x,y)</pre>	Allows you by clicking on the point to identify the item. Right-Mouse click ends the ses- sion.	
<pre>locator()  plot(x,y,type="b") points(x,x,col="red") legend(1,100,legend= c("A","B"),</pre>	Allows you to identify an arbi- trary point in the plot, for ex- ample to place a legend at the right place Add a legend to the above graph. The place (1,100) is in the coordinates of the graph! It can simply be picked by us- ing locator. lty gives the line types, -1 is no line, and pch gives the point type.	
	$ \begin{array}{c}                                     $	

#### 1.1.2 Distributions

Typcial distributions are included in the following form:

ddist(x,) = $f_{\dots}(x)$ :	density or probability functions
pdist(x,) = $F_{\dots}(x)$ :	cumulative distribution function: $\mathbb{P}(X \leq x)$ for $X \sim F$
qdist( y,) $=F_{\dots}^{-1}(y)$ :	quantilefunction ,
r <i>dist</i> ( n,) :	generates $n$ random variables

#### 1 First steps

of the distribution *dist. dist* can be for example: norm, exp, binom, beta, gamma, t, norm and many others (see table in the appendix). So **dnorm** gives the density of the normal distribution, **pexp** gives  $1 - e^{-x}$ , the cdf of the Exp(1)-distribution, **qunif** is the inverse cdf of the uniform distribution, i.e. the identity on [0, 1] and **rbeta(100,0.5,0.5)** simulates 100 i.i.d. Beta(0.5,0.5)-distributed random variables.

**Exercise 2.** Plot the densities function of the normal, the t and the  $\Gamma$  distributions. Vary with different parameters and colors in the plot.

For example, you could do the following:

 $x \le seq(-2,2,by = 0.01)$ plot(x,dnorm(x),type="l") lines (x,dnorm(x,mean=1,sd=1.5), type="l",col =2) The functions x\*2 and x\*3  $\int_{0}^{0} \int_{0}^{0} \int$ 

dnorm(x,1,2) gives a normal distribution with *standard deviation* of 2 and not variance of 2.

Simulation of random variables in R is very easy. Try for example the following:

Simulations	
<pre>data &lt;- rnorm(100) mean(data) var(data) sd(data) summary (data) quantile( data, probs=c( 0, 0.2, 0.9))</pre>	This gives you some statistics on the data.

**Exercise 3.** You can experiment, plot and so on. Try different distributions like t and  $\Gamma$  to get a feeling on them. Try help on sd, var, median, max, min, fivenum, IQR.

#### 1.1.3 Further statistics

Compute histograms:<sup>1</sup>



Try also **smoothScatter** or the following example on nonparametric density estimation:

<sup>&</sup>lt;sup>1</sup>You can look at Bret Largets introdution: http://www.stat.wisc.edu/~larget/R/eda-R.pdf for further explanations and examples.



Now if you feel well with R, go ahead and try some of your favorite simulations.

**Exercise 4.** Monte-Carlo experiment. What is  $\mathbb{E}(\xi^n)$  with n = 1, 2, 3, 4 when  $\xi$  is normally distributed. Or exponential, Gamma, t. Solve the question by Monte-Carlo:

> x <- rnorm(100)	
> y <- x^4	<pre>#transformation with n=4</pre>
> mean(y)	#The Monte Carlo estimate of the 4th moment

The background is of course the strong law of large numbers.

If you feel an expert, then try the following (difficult) financial application:

**Exercise 5.** Simulate a Brownian motion. Simulate a geometric Brownian motion (the Black-Scholes Model). Compute the price of a call option via Monte-Carlo, i.e. simulate 1000 payoffs and compute the mean

Hints: if  $(W_t)_{t\geq 0}$  is a Brownian motion, it has independent and stationary increments. Moreover the increments are normally distributed:

$$W_{t+\Delta} - W_t \sim \mathcal{N}(0, \Delta).$$

We obtain a Brownian motion by *accumulating* independent, normally distributed random variables. Use the command **cumsum** for this. Simulate paths and plot for a double check. Finally, simulated  $W_1$ , the value of the Brownian motion at 1 1000 times and give a histogram. Is it a normal distribution (try qqplot). Has it mean zero? Has it variance 1? Yes - then you got it!

#### 1.1.4 Defining our own functions

Of course a very powerful method is defining your own function. We start by giving a function for plotting a nice graph of a density. Note the **substitute** used for obtaining greek letters and inserting the values of variables in the title of the plot.

```
gnorm <- function(x) {
    m=0    # mean
    s=1    # sd
    y <- dnorm(x,m,s)
    plot(x,y,type="l",
        main =substitute(paste("Normal Density with ",mu == m,
        ", ",sigma == s),list(m=mu,s=sigma)))
}</pre>
```

We call this function for example by gnorm(seq(-2,2,by=0.1)). Simply typing gnorm recalls the definition of this function.

This section will have a focus on simulation, with a small section on estimation at the end. We start with the simulation of multivariate distributions <sup>1</sup> (.mnorm, .mt, .mghyp in R) and give important implications for estimating correlations with heavy tails.

#### 2.1 Multivariate models

Now we turn to the multivariate distributions. Define an easy function for the multivariate normal as follows<sup>2</sup>. To address a covariance (or correlation) matrix simply by the correlations, we use equicorr

```
equicorr <- function (d, rho)
{
    if (rho < (-(d - 1)^(-1)))
        stop(paste("rho must be at least", -(d - 1)^(-1)))
    J <- matrix(rho, nrow = d, ncol = d)
    D <- diag(rep(1 - rho, d))
    J + D
}</pre>
```

Taking  $X = \mu + AZ$  with Z being a vector of independent, standard normal variables gives a vector of normal variables with mean  $\mu$  and covariance matrix  $\Sigma = AA'$ , which we use in the following. Recall that the Cholesky-Decomposition of  $\Sigma$  gives A.

<sup>&</sup>lt;sup>1</sup>The functions .mnorm .mt are taken from the QRM lib. See the appendix for details and code.

<sup>&</sup>lt;sup>2</sup>This and the following functions are taken from the QRMlib. We list them again in the appendix, for your reference.

```
A <- t(chol(Sigma))
X <- matrix(rnorm(n * d), nrow = n, ncol = d)
mu.matrix <- matrix(mu, nrow = n, ncol = d, byrow = TRUE)
return(t(A %*% t(X)) + mu.matrix)
}</pre>
```

This function gives us an easy way to call a simulation of a multivariate normal distribution.



#### 2.1.1 The probability and quantile transforms

An imporant idea needed here is the so-called *probability transform*: for a *continuous* random variable X with distribution function F the random variable

F(X)

is uniformly distributed.

**Exercise 6.** Implement a test for this: Simulate a t-distribution and compute the (probability) transform F(X). Test if this is uniformly distributed (Kolmogorov-Smirnov, or via a qqplot)

From a uniform random variable U we obtain a random variable with cumulative distribution function via the *quantile* transform:

$$X \sim F^{-1}(U).$$

> x <- runif(100)
> y <- qbeta(x)
> hist(y)

We can also test this via a nonparametric estimate of the cdf, the *empirical distribution* function. This is implemented in the function **ecdf** from the package stats:



### 2.2 Copulas

For computing or simulation a copula we take a random vector  $(X_1, X_2)$  and transform it to

 $(F_1(X_1), F_2(X_2))$ 

The distribution of this vector is a *copula*. For any copula, there exists a random vector, such that its cdf is the copula. In this section we aim at simulating some copulas. The Gauss copula is obtained from the normal distribution:



The t-copula shall be compared to the Gauss copula and we define a function for simulating multivariate t-random variables.

Lets plot the *t*-random variables and the probability transforms.

```
data <- rmt(2000,rho=0.4,df=4)
plot(data,main="t")
U <- pt(data,df=4)
plot(U,main="t-copula")</pre>
```

**Exercise 7.** Simulate 100 Gaussian vectors  $(X_i, Y_i)$  with correlations  $\rho = -0.8, 0, 0.8$  and transform  $X_i$  and  $Y_i$  to exponential, log-normal and normal variables with mean and variances of your choice. Plot the resulting data and the associated probability transforms (copula).

2-dimensional Normal and <i>t</i> -random variables		
<pre>data1 &lt;- rmnorm(1000,d=2,rho=0.5) data2 &lt;- rmt(1000,d=2,rho=0.5) var(data1) var(data2)</pre>	We use <b>rmnorm</b> and <b>rmt</b> to generate the 2-dimensional random variables. Then we check for the resulting variances. Correlation is estimated via <b>for</b> .	
cor(data1) cor(data2)		
<pre>cor.test(data2[,1],data2[,2])</pre>	If we want to have a confidence interval for the correlation, we use cor.test	

Next, we visualize these data.

We first compute xmin,... to achieve the same scaling on xmin=min(c(data1[,1],data2[,1])) both graphs. The output is split xmax=max(c(data1[,1],data2[,1])) into two parts, using the parymin=min(c(data1[,2],data2[,2])) command. par(op) switches ymax=max(c(data1[,2],data2[,2])) back to the single output win $dow^3$ . par(mfrow=c(2,1))plot(data1,xlab="x\_i",ylab="y\_i", Multivariate Normal, p=0.5 xlim=c(xmin,xmax),ylim=c(ymin,ymax), main="Multivariate Normal, rho=0.5") plot(data2,xlab="x\_i",ylab="y\_i", xlim=c(xmin,xmax),ylim=c(ymin,ymax), main="Multivariate t\_3, rho=0.5")

Clearly, the *t*-distribution shows much more outliers and heavy tails in comparison to the normal distribution. The variances, however, are different and after the following resealing still this difference appears.

data2[,1] <- sqrt(var(data1[,1])/var(data2[,1]))\*data2[,1]
data2[,2] <- sqrt(var(data1[,2])/var(data2[,2]))\*data2[,2]</pre>

#### Correlation as measure of dependence

In financial application it is very sensible to use correlation in the right way as we discuss in the course. Here we illustrate this with the following example. We compute normal random variables with correlation of 0.8 and the transform them via the nonlinear function **exp**. The resulting correlation is much smaller! However, spearmans  $\rho_S$  does not show this effect. It is a dependence measure invariant to monotone transformations, a very suitable property in financial data. It is also less sensible to outliers.

<pre>set.seed(13) sigma &lt;- 4 rho &lt;- 0.8 Sigma &lt;- matrix(c(1,rho*sigma ,</pre>	We use set.seed to guaran- tee we work all on the same random numbers. The esti- mated correlation (0.35) differs largely from the initial correla- tion (0.8). Why is this the case? Illustrate this by plotting the data.
<pre>cor(y,method="spearman")</pre>	Try also alternatively Kendall's tau and Spearman's rho.

If the data is heavy tailed, sensitive measures like mean or sample correlation may severly fail to estimate the correct values. We show this using kendalls'tau  $\rho_{\tau}$  in comparison to linear correlation  $\rho$  on  $t_3$  data. Recall the we have  $\rho_S(X,Y) = \frac{6}{\pi} \arcsin \frac{\rho(X,Y)}{2} \approx \rho(X,Y)$  and  $\rho_{\tau}(X,Y) = \frac{2}{\pi} \arcsin \rho(X,Y)$ .



#### 2.2.1 A first look at copulas

We simulate a number of copulas, starting with normal and *t*-copulas. The difference to our previous simulations with **rmnorm** is that we have to transform the marginals to a uniform distribution. This can be done by using the empirical cumulative distribution function (cdf) (which is an approximation, then) or by using the underlying cdf, which we call *probability transform*.



**Exercise** Simulate different mean-variance mixture distributions and their copulas. Compare the copulas obtained by the probability transform to the ones obtained by the empirical cdf (use ecdf).

### 2.3 Estimating copulas

Typically, copulas can be estimated via maximum-likelihood methods. This requires a more sophisticated implementation, in particular because the density is not so simple. You find the code from the QRMlib in QRMlibparts.R. Alternatively, you simply install the QRMlib. If the package is installed you can load it by

library(QRMlib)

#### 2.3.1 Estimation via rank correlations

If the number of degrees of freedom is known, it remains only to estimate the correlation parameter. As indicated above, this can be done via Spearman's  $\rho$  or Kendall's  $\tau$ .

Estimation of the correlation coefficient		
<pre>N &lt;- 100000 n &lt;- 100 r1 &lt;- rep(0,N);r2 &lt;- r1;r3 &lt;- r1 pb &lt;- txtProgressBar(style=3) for (i in 1:N) { data &lt;- rmt(15,rho=0.5) r1[i] &lt;- cor(data)[1,2] r2[i] &lt;- sin(cor(data,method="spearman")[1,2]*pi/6)*2 r3[i] &lt;- sin(cor(data,method="kendall")[1,2]*pi/2) setTxtProgressBar(pb, i/N) }</pre>	We use the txtProgressBar to follow the progress of this longer simulation. Using a smaller N speeds it up, leading to similar results. The output is [1] 0.489 0.499 0.0284 [1] 0.470 0.477 0.0081 [1] 0.491 0.498 0.0082	
c(mean(r1), median(r1), var(r1)); 		



As a next step we want to test the maximum-likelihood estimation of the copulas. We test some examples. In the  $QRMlib^4$  we find the necessary tools.

Estimating a <i>t</i> -copula		
data <- rmt(1000,df=5,rho=0.8)	LS distribution, p=0.8	
<pre>list(Means=c(mean(data[,1]),mean(data[,2])),     Variances=var(data),     Correlation=cor(data)[1,2])</pre>	<pre>\$Means [1] -0.017031 0.009217 \$Variances        [,1] [,2] [1,] 1.472639 1.134481 [2,] 1.134481 1.452208 \$Correlation [1] 0.7757727</pre>	
fit.norm(data)	Gives the exact result as above with log-likelihood ll.max = -2756.518	
fit.mst(data)	The result is nu=5.23 degrees of freedom and a correlation of 0.801 and 11.max = -2648.338	

<sup>&</sup>lt;sup>4</sup>This library provides a lot of fitting algorithms: fit.AC, fit.Archcopula2d, fit.gausscopula, fit.mNH, fit.mst, fit.norm, fit.tcopula, fit.tcopula.rank besides other fitting routines for univariate distributions or extreme-value methods.

The higher likelihood under the *t*-copula suggest that this gives a better fit. This is *not* a test for normal copula agains a *t*-copula, just a simple fitting argument (Can you name the difference?).

#### 2.3.2 The generalised hyperbolic distribution

Next, we turn to the important class of generalized hyperbolic distributions. We use the notation  $X \sim GH_d(\lambda, \chi, \psi, \mu, \Sigma, \gamma)$ . The GH-distribution is a mixture:

$$X = \mu + \gamma W + \sqrt{W}AZ$$

where W has a generalized inverse Gaussian (GIG) distribution,  $W \sim GIG(\lambda, \chi, \psi)$ . So  $\mu$  is the mean,  $\gamma$  is the skewness parameter and  $\Sigma = AA'$  the covariance matrix (before mixing). As is easy to see by the Fourier-transform, the GH distribution is closed under linear transformations, i.e. BX + b has distribution  $GH_d(\lambda, \chi, \psi, B\mu + b, B\Sigma B', B\gamma)$ .<sup>5</sup> If  $\lambda = \frac{1}{2}(d+1)$ , we call the distribution a *d*-dimensional hyperbolic distribution. We obtain the  $t_n$  distribution with  $\lambda = -\frac{n}{2}, \chi = n, \psi = 0$ ; if  $\gamma = 0$  this is the (classical) unskewed  $t_n$ -distribution.

<sup>&</sup>lt;sup>5</sup>There are many special cases, hyperbolic, NIG, Variance Gamma and so on.



Next, we aim at estimating the parameters of the generalized hyperbolic distribution. First, in the univariate and then in the 2-dimensional case. Simulations are used to analyze the performance of the estimation.

	we obtain		
N<- 100	means	variances	
n<- 500	0.9926	0.0172	
psi <- rep(0,N) chi <- rep(0,N)	1.0503	0.0396	
rho <- rep $(0,N)$	0.2010	0.0013	
<pre>for (i in 1:N ){ fit &lt;- fit.mNH(rmghyp(1000,-0.5,1,1,rho=0.2)) psi[i] &lt;- fit\$mix.pars[2] chi[i] &lt;- fit\$mix.pars[3] rho[i] &lt;- fit\$correlation[1,2] }</pre>			

#### A data example

This section aims at analyzing financial data. We first download data conveniently from the yahoo finance sites with the package fImport. Alternatively, any data in .csv (or other) format can be easily imported, for example with the comannds read.table, read.csv. We choose the stock prices from BBVA and Santander (NY), in Dollars.



```
The data analysis gives
                                                     log likelihood max
mod.GAUSS <- fit.norm(dx )</pre>
mod.NIG <- fit.mNH(dx ,</pre>
                                                    GAUSS
                                                                  17332.2
        symmetric=FALSE, case="NIG")
mod.HYP <- fit.mNH(dx ,</pre>
                                                    t
                                                                  18177.9
         symmetric=FALSE,case="hyp")
                                                    NIG (symm)
                                                                  18198.5
mod.t <- fit.mst(dx )</pre>
                                                    GH (symm)
                                                                  18165.9
mod.NIGs <- fit.mNH(dx ,</pre>
         symmetric=TRUE, case="NIG")
                                                    NIG
                                                                  18199.8
mod.HYPs <- fit.mNH(dx ,</pre>
                                                    GH
                                                                  18167.2
         symmetric=TRUE,case="hyp")
                                                   The best fit is in both cases,
                                                   symmetric and asymmetric pro-
mod.GAUSS$11.max
                                                   vided by the NIG distribution.
# and similar
                                                    lambda
                                                               chi
                                                                      psi
                                                     -0.50
                                                               0.00 1310.6
                                                    gamma
                                                     -1.991 -2.671
```

#### 2.4 Definitions

This functions were used above, taken from QRMlib

```
# Generate a correlation matrix with equal correlations
equicorr <- function (d, rho)
{
    if (rho < (-(d - 1)^{-1}))
        stop(paste("rho must be at least", -(d - 1)^(-1)))
    J <- matrix(rho, nrow = d, ncol = d)</pre>
    D \leq diag(rep(1 - rho, d))
    J + D
}
# Generate multivariate normal random variables
rmnorm <- function (n, Sigma = equicorr(d, rho),</pre>
                     mu = rep(0, d), d = 2, rho = 0.7)
 {
    d <- dim(Sigma)[1]</pre>
    A <- t(chol(Sigma))
    X <- matrix(rnorm(n * d), nrow = n, ncol = d)</pre>
    mu.matrix <- matrix(mu, nrow = n, ncol = d, byrow = TRUE)</pre>
```

```
return(t(A %*% t(X)) + mu.matrix)
}
```

For the multivariate t-distribution we use the representation  $t = \mu + \sqrt{W}AZ$  where Z is standardnormal and W has an inverse Gamma distribution.

## 3 Risk measures

In this section we take a closer look at the estimation of risk measures, in particular value-at-risk and expected shortfall. We assume that we have a history of *losses* and want to predict or control outcomes of a future loss. Xonsider the i.i.d. case, i.e. where we observe  $X_1, \ldots, X_n$  random variables which are independent and identically distributed and have the same distribution like  $X = X_{n+1}$ , the future loss. We want to estimate the risk regarding the unknown future outcome of X. Denote the cdf of X by F.

If F is continuous, or at least if  $\mathbb{P}(X = \alpha)$ , then the value at risk of X at confidence level  $\alpha$  (typically 0.95 or 0.99) is

$$\operatorname{VaR}_{\alpha}(X) := F^{-1}(\alpha)$$

 $F^{-1}(\alpha)$  is a particular quantile of X. If X is continuous at  $\alpha$ , the quantile to the level  $\alpha$  is unique and we denote it by  $q_{\alpha}(X)$ . It coincides with  $F^{-1}(\alpha)$  in this case. If  $X \sim \mathcal{N}(\mu, \sigma^2)$ , then

$$\operatorname{VaR}_{\alpha}(X) = \mu + \sigma \Phi^{-1}(\alpha),$$

where  $\Phi$  is the cdf of the standard normal distribution. In the normal context valueat-risk is coherent, otherwise it is not, because the subadditivity fails. The second risk measure what we want to consider is the expected shortfall (average value-at-risk or conditional value at risk). It is defined by

$$\mathrm{ES}_{\alpha}(X) = \frac{1}{1-\alpha} \int_{q_{\alpha}(X)}^{1} q_{u}(X) du.$$

Note that for this definition we do not need continuity of X. If X is continuous, we also have that

$$\operatorname{ES}_{\alpha}(X) = \mathbb{E}(X|X > \operatorname{VaR}_{\alpha}(X)).$$

In the Gaussian case, i.e. if  $X \sim \mathcal{N}(\mu, \sigma^2)$ , we obtain

$$\mathrm{ES}_{\alpha}(X) = \mu + \sigma \frac{\phi(\Phi^{-1}(\alpha))}{1 - \alpha}.$$

We start with an analysis of the IBEX index.



To compute the value-at-risk we first *assume* that the index loss has a normal distribution with mean -0.35 and sd of 150.

	The obtained risk measures are
<pre>VaR.Gauss &lt;- function (alpha=0.95,mu,sigma) { mu + sigma* qnorm(alpha)</pre>	VaR <sub>0.95</sub> 246.37 $ES_{0.95}$ 309.06
}	$VaR_{0.99}$ 348.60 $ES_{0.99}$ 399.43
ES.Gauss <- function(alpha=0.95,mu,sigma) {	
<pre>mu + sigma/(1-alpha)*dnorm(qnorm(alpha)) }</pre>	



Next, we want to asses the quality of the risk measures. At the moment we employ two estimating possibilities:

(i) Naive: we substitute the estimated parameters  $\hat{\mu} = \text{mean}(X)$  and  $\hat{\sigma} = \text{sd}(X)$ . This gives the estimate

#### VaR.Gauss(alpha,mean(data),sd(data))

(ii) Empirical: this uses the empirical quantile and is simply implemented by

```
VaR.emp <- function(x,alpha){
quantile(x,alpha)
}</pre>
```

We analyze the quality of this measures by a Monte-Carlo simulation:



#### 3.1 Performance of the risk estimates

This is, however, until now a statistical analysis. In a financial sense we are much more interested in the question *how often* is the calculated risk capital sufficient to cover the occurring losses? This shall be addressed in the following. We perform a method similar to a backtesting approach and the routines can simply be extended to this.

```
mu <- -0.3525174
sigma <- 150.0785
N<- 1000
n<- 100  # Learning period
M<- 100  # Backtesting period
alpha <- 0.95
var.true <- VaR.Gauss(alpha,mu,sigma)
var.est1 <- rep(0,N)
var.est2 <- rep(0,N)
var.est3 <- rep(0,N)
counts <- rep(0,4)</pre>
```

```
for (i in 1:N){
data <- rnorm(n,mu,sigma)
var.est1[i] <- VaR.emp(data,alpha)
var.est2[i] <- VaR.Gauss(alpha,mean(data),sd(data))
var.est3[i] <- mean(data)+sd(data)*qt(alpha,n-1)
newperiod <- rnorm(M,mu,sigma)
counts[1] <- counts[1]+ sum(newperiod>var.est1[i])
counts[2] <- counts[2]+ sum(newperiod>var.est2[i])
counts[3] <- counts[3]+ sum(newperiod>var.est3[i])
counts[4] <- counts[4]+ sum(newperiod>var.true)
}
```

The output is as follows (counts/M/N) :

Method	Empirical	Naive	t	True VaR
Perc. failure	0.05860	0.05320	0.05166	0.05005

Surprisingly, all the risk measures perform quite bad. This is due to the well-known effect that the distribution has to be estimated and estimating the parameters changes the original normal distribution to a t distribution. Still, it is surprising that the according t-estimate propagated in the literature performs so bad. This is due to the fact that the estimator is *biased in probability*. There is a theoretical solution to this, which we discussed in class. Here we aim at finding an empirical solution to this. We aim at computing the quantile factor q such that

$$\operatorname{VaR}_{0.95}^* := \operatorname{mean}(\operatorname{data}) + \operatorname{sd}(\operatorname{data}) * q$$

does produce an average number of  $1 - \alpha$  failures.

```
# Estimate the quantile level q empirically
N<- 1000
n<- 100 # Learning period
M<- 100 # Backtesting period
newperiod <- rep(0,N*M)
for (i in 1:N){
        data <- rnorm(n,mu,sigma)
        newperiod[(1+(i-1)*M):(i*M)] <- (rnorm(M,mu,sigma)-mean(data))/sd(data)
}
```

The outcome is surprisingly clear:

By simply adding

```
var.est4[i] <- mean(data)+sd(data)*1.668395</pre>
```

We can incorporate our new VaR-estimator in the above test and obtain

Method	Empirical	Naive	t	New VaR	True VaR
Perc. failure	0.05860	0.05320	0.05166	0.5051	0.05005

In accordance with our theoretical considerations the new factor is very close to

$$\sqrt{\frac{n+1}{n}}t_{n-1}.$$

Accordingly we obtain the *modified* VaR estimator by

$$VaR^*_{\alpha} := mean(data) + sd(data) * qt(alpha) * sqrt((n+1)/(n)).$$
(3.1)

**Exercise 8.** Translate this considerations to a t-distribution and proceed with the following steps:

- Estimate a t (or a generalised inverse Gaussian) distribution from the IBEX data.
- Propose VaR-estimates: naive estimation, empricial estimation and an estimation with is according to (3.1).
- Study mean, variance and distribution of these estimates with a simulation study.
- Implement a backtesting procedure and analyze as above how this estimations perform.

**Exercise 9.** What are appropriate criteria for the expected shortfall? How can this mechanisms be transported?

# 4 Estimation of diffusions and affine models

We discuss the implementation of some estimation methods for continuous, affine, onedimensional diffusions. A great survey on the estimation methods can be found in [?]. Essentially, we consider models of the class

$$dX_t = \mu(X_t, \theta)dt + \sigma(X_t, \theta)dW_t,$$

i.e. continuous Markov processes. Famous examples are the affine models and, in particular, the Vasicek and the Cox-Ingersoll-Ross models.

#### 4.1 Simulation

The *Vasicek* model is a special Ornstein-Uhlenbeck process. In classical notation we state it by

$$dX_t = \kappa(\theta - X_t)dt + \sigma dW_t.$$

It has the explicit solution<sup>1</sup>

$$X_t = \theta + (X_0 - \theta)e^{-\kappa t} + \sigma e^{-\kappa t} \int_0^t e^{\kappa s} dW_s$$

For a simulation we can use this explicit solution, which is however not feasible for more general diffusions. In these cases we have the possibility to approximate the solution by discretization. The simplest one is the *Euler-Maruyama* discretization,

$$x_{t_i} = \mu(x_{t_{i-1}})(t_i - t_{i-1}) + \sigma(x_{t_{i-1}})\epsilon_i$$

where  $\epsilon_1, \epsilon_2, \ldots$  are independent and  $\epsilon_i \sim \mathcal{N}(0, t_i - t_{i-1})$ . Of a faster convergence is the Milstein scheme, where

$$x_{t_i} = x_{t_{i-1}} + \mu(x_{t_{i-1}})(t_i - t_{i-1}) + \sigma(x_{t_{i-1}})\epsilon_i + \frac{\sigma(x_{t_{i-1}})}{2}\frac{\partial\sigma(x_{t_{i-1}})}{\partial x}(\epsilon_i^2 - (t_i - t_{i-1}))$$

In the Vasicek model, both methods coincide. For  $t_i - t_{i-1}$  small enough, the methods are very close:

<sup>&</sup>lt;sup>1</sup>See Cucchiero, for example

```
vas.sim <- function (n,theta,sigma,kappa,Delta,vas0,method="exact") {
    simul <- rep(0,n); simul[1] <- vas0
    for (i in 2:n){
        simul[i] <- theta + (simul[i-1]-theta)*exp(-1*kappa *Delta)
            + sigma*rnorm(1,0,sqrt((1-exp(-2*kappa*Delta))/2/kappa))
        }
    return (simul)
}</pre>
```



**Exercise 10.** Implement the simulation of the CIR process with all three methods and compare their performance.

The simulation of the CIR process is much more difficult, as you will experience. What to do if the process gets below zero?

#### 4.2 Maximum-Likelihood estimation

For the maximum-likelihood estimation we rely on R's routine optim. In the Vasicek model we have the exact density and can simply maximise the log-likelihood. We assume that we observe  $x_{i\Delta}$ , i = 0, ..., n - 1, i.e. n data points. The first point  $x_0$  is deterministic. Then

$$ll(x;\theta) = -\frac{n-1}{2}\ln(2\pi) - \frac{n-1}{2}\ln(V) - \frac{1}{2V}\sum_{i=1}^{n-1}(x_{i\Delta} - \beta - (x_{(i-1)\Delta} - \beta)e^{-\alpha\Delta})^2,$$
$$V = \frac{\sigma^2}{2\alpha}(1 - e^{-2\alpha\Delta}).$$

We maximize<sup>2</sup> this function with respect to  $\theta = (\alpha, \beta, \sigma)'$ . We will see that estimation of  $\beta$  and  $\sigma$  is by far simpler than estimating  $\alpha$ .

```
vas.ll <- function (params,Delta,Data) {</pre>
  alpha <- params[1]
  beta <- params[2]</pre>
  sigma <- params[3]</pre>
  n <- length(Data)</pre>
  vassigma2 <- (sigma^2)*(1-exp(-2*alpha*Delta))/2/alpha</pre>
  summe <- -1/2/vassigma2* sum ((Data[2:n]-beta-</pre>
        (Data[1:(n-1)]-beta)*exp(-1*alpha*Delta))^2)
  return((1-n)/2*log(2*pi) - (n-1)/2*log(vassigma2)+summe)
}
vas.mle<- function (Delta,Data,output=FALSE){</pre>
    startvalue <- c(0.1, 0.1, 0.1) # arbitrary
    MLE.out <- optim (startvalue,vas.ll,gr = NULL, method = "Nelder-Mead",
        lower = -Inf, upper = Inf, control = list(fnscale=-1),
        hessian = FALSE, Delta, Data)
    return (c(MLE.out[[1]][1],MLE.out[[1]][2],MLE.out[[1]][3]))
}
```

It should be noted that optim is a numerical procedure which depends on the start value. The Nelder-Mead method seems to be quite robust. The BFGS method has a better performance, but choosing  $\alpha = \beta = \sigma = 0.5$  and starting with 0.1 leads to convergence but no sensible result.

We compare our results to the ones from Hurn et. al (2007) in the following exercise.

**Exercise 11.** Simulate 2000 runs of a MLE estimation of a Vasicek model with parameters  $\alpha = 0.2, \beta = 0.08$  and  $\sigma = 0.1$ . Assume that you observe in each run 500 data points with  $\Delta = 1/12$  and  $x_0 = \beta$ .

We state the outcome in terms of mean error and root mean square error  $(N^{-1}\sum_{i=1}^{N}(\hat{\theta}_{i}-\theta))$  and  $\sqrt{N^{-1}\sum_{i=1}^{N}(\hat{\theta}_{i}-\theta)^{2}}$ . We use the parameters  $\theta_{1} = (0.2, 0.08, 0.1)$  and  $\theta_{2} = (0.3, 0.4, 0.5)$  for a simulation study. The start value of the optimization is  $\theta_{0} = (0.1, 0.1, 0.1)'$ .

<sup>&</sup>lt;sup>2</sup>Typically it may happen that the maximization does not converge. This should be covered by using checking if MLE.out returns non-zero convergence.

	Mean error in $\alpha$ (RMS error in $\alpha$ )	Mean error in $\beta$ (RMS error in $\beta$ )	Mean error in $\sigma$ (RMS error in $\sigma$ )
MLE $\theta_1$	0.110200	0.000246	-0.002569
	(0.183036)	(0.077009)	(0.023177)
MLE $\theta_2$	0.100273	-0.031805	0.001530
	(0.197201)	(0.288133)	(0.016250)
MLE. corr $\theta_1$	0.108214	-0.000351	0.000142
	(0.180004)	(0.076279)	(0.003229)

#### 4 Estimation of diffusions and affine models

It is important that these estimators are *biased*! Even if the mean error is very small, a **t.test** rejects the hypothesis that the bias is zero immediately. So for MLE.corr we crudely estimated the bias by simulation and subtracted it. In contrast to typical bootstrap approaches this did not give an increasing variance, so this seems to be currently the best way to estimate the parameters. The estimation of  $\alpha$  should be possible to improve, however. The t.test for the bias now does not reject on  $\hat{\beta}$  and  $\hat{\sigma}$ .

Note !

We used the following code:

```
alpha=0.2; beta=0.08; sigma=0.1; delta=1/12
n=500; N=2000
thetahat = array(rep(0,3*N),dim=c(N,3))
for (i in 1:N){
 thetahat[i,]= (vas.mle(delta,vas.sim(n,alpha,beta,sigma,delta,0))
- c(alpha, beta, sigma))
}
cat("\n Mean errors: \n")
print(c(mean(thetahat[,1]),mean(thetahat[,2]),mean(thetahat[,3])))
cat("\n RMS erros: \n")
print(c(sqrt(mean(thetahat[,1]^2)),sqrt(mean(thetahat[,2]^2))
      ,sqrt(mean(thetahat[,3]^2))))
cat("\n Test for bias: \n")
print(c(t.test(thetahat[,1],alternative="two.sided")$p.value,
    t.test(thetahat[,2],alternative="two.sided")$p.value,
    t.test(thetahat[,3],alternative="two.sided")$p.value),digits=3)
```

The density of the (centered) estimators are easily plotted:



and for the second sets of parameters:



In particular, the plots of the estimators for  $\alpha$  and  $\beta$  show significant skewness. Also the bias is illustrated (not always, though). It is important to recall that we have N = 2000 observations.

#### 4.2.1 GMM

The generalized method of moments (GMM) is a flexible and powerful method for estimation. We follow Chaussé (2010) and give a short outline and the implementation for the estimation of affine processes with R. In this regard we will be able to profit from the gmm-package available.

Assume that we aim at estimating  $\theta_0 \in \mathbb{R}^p$  and we have q > p moment conditions of the form

$$\mathbb{E}(g(\theta_0, X_i)) = 0, \quad i =, \dots, n$$

 $X_1, \ldots, X_n$  is the observation or a transformation of it, in our case we would see a discrete observation of a stochastic process.  $\theta_0$  is the unique solution of the above

equation and element of a compact space. We also need some boundedness of higher moments (see ...).

As q is typically greater than q we have no solution of

$$\bar{g}(\theta) := \frac{1}{n} \sum_{i=1}^{n} g(\theta, x_i),$$

(which otherwise would be our estimator). We therefore rely on minimizing a quadratic distance

 $\bar{g}(\theta)^{\top}W\bar{g}(\theta).$ 

It can be shown that the optimal weight matrix W is

$$W^* = \left(\lim_{n \to \infty} \operatorname{Var}(\sqrt{n}\bar{g}(\theta_0))\right)^{-1}.$$

This matrix, however, must be estimated and there are different schemes available for this (two-step as in Hansen (1982) or iterative procedures as in Hansen et. al (1996)). Under weak conditions we have asymptotic normality and consistency.

**Example 4.2.1.** Suppose we have i.i.d. observations which are  $\mathcal{N}(\mu, \sigma^2)$  distributed. We could use the following moment conditions:

$$\mathbb{E} \begin{pmatrix} X_i - \mu \\ (X_i - \mu)^2 - \sigma^2 \\ X_i^3 - \mu(\mu^2 + 2\sigma^2) \end{pmatrix} = 0$$

to estimate with GMM. Note that we do not use the density, i.e. the method will be clearly less efficient as maximum-likelihood. On the other side we gain in robustness agains miss specification of the density. Implementation is done as follows (borrowed from Chaussé, 2010)

```
g1 <- function(tet, x) {
    m1 <- (tet[1] - x)
    m2 <- (tet[2]^2 - (x - tet[1])^2)
    m3 <- x^3 - tet[1] * (tet[1]^2
        + 3 * tet[2]^2)
    f <- cbind(m1, m2, m3)
    return(f) }

Dg <- function(tet, x) {
    G <- matrix(c(1, 2 * (-tet[1] + mean(x)),
        -3 * tet[1]^2 - 3 * tet[2]^2,
        0, 2 * tet[2], -6 * tet[1] * tet[2]),
        nrow = 3, ncol = 2)
    return(G) }

x <- rnorm(200, mean = 4, sd = 2)
gmm(g1, x, c(mu = 0, sig = 0), grad = Dg))
</pre>
```

This runs the hmm function with moment conditions given in the function g1 and data in x. The starting vector is simply (0,0)with names given. The gradient is provided in Dg, which improves the performance.

Many existing methods can be seen as a special case of GMM, as for example the maximum-likelihood estimation.

#### 4.2.2 GMM for affine models

Considering the Vasicek model, we again use the Euler discretization

$$x_{t_i} - x_{t_{i-1}} \approx \alpha(\beta - x_{t_{i-1}})(t_i - t_{i-1}) + \epsilon_i;$$

 $\epsilon_1, \ldots$  are independent and  $\sim \mathcal{N}(0, \sigma^2(t_i - t_{i-1}))$ . This leads to the following moment conditions;

$$\mathbb{E}\begin{pmatrix} \epsilon_i \\ \epsilon_i X_{t_{i-1}} \\ \epsilon_i^2 - \sigma^2 * (t_i - t_{i-1}) \\ (\epsilon_i^2 - \sigma^2 * (t_i - t_{i-1})) X_{t_{i-1}} \end{pmatrix} = 0$$

```
vas.g <- function(theta, x) {
    t <- length(x)
    et <- diff(x) - theta[1]*( theta[2] - x[-t])*Delta
    ht <- et^2 - (theta[3])^2*vas.gmm.Delta
    g <- cbind(et, et * x[-t], ht , ht * x[-t])</pre>
```

return(g)

}

We call of the function hmm as follows: we set vas.gmm.Delta as global variable using <-- The function does not always converge in which case we obtain a warning. Then the starting values must be improved, eg. by using a linear regression or a moment estimator. It is remarkable that using the explicit solution of the moments does not provide an improvement of the method.

```
vas.gmm<- function (Delta,data,output=FALSE,tet0 = c(0.1,0.1,0.1) )</pre>
{
    vas.gmm.Delta <<- Delta</pre>
                                # global
    gmm_res <- gmm(vas.g, data, t0 = tet0,
       control = list(maxit = 1000, reltol = 1e-10))
    coef(gmm_res)
```

}

	Mean error in $\alpha$	Mean error in $\beta$	Mean error in $\sigma$
	(RMS error in $\alpha$ )	(RMS error in $\beta$ )	(RMS error in $\sigma$ )
MLE $\theta_1$	0.110200	0.000246	-0.002569
	(0.183036)	(0.077009)	(0.023177)
MLE $\theta_2$	0.100273	-0.031805	0.001530
	(0.197201)	(0.288133)	(0.016250)
$\mathrm{GMM}^3 \; \theta_1$	0.111979	-0.002128	0.000158
	(0.181764)	(0.076595)	(0.003086)
GMM $\theta_2$	0.101213	0.002594	-0.009704
	(0.183155)	(0.259188)	(0.018861)

The performance of the estimators is best viewed with the density plots of the bias of our 2000 simulations: for  $\theta_1 = (0.2, 0.08, 0.1)'$  we obtain a small advantage in the first coordinate while the estimator of  $\sigma$  has a bias. Note that the precision in  $\sigma$  is by far higher as in the two other coordinates. For  $\theta_2 = (0.3, 0.4, 0.5)'$  this pattern becomes clearer: for  $\beta$  the GMM performs better while for  $\sigma$  there is a clear bias.

4 Estimation of diffusions and affine models



Exercise 12. Implement a GMM estimator of a CIR model.

## **A** Commands

The distributions (norm, gamma, beta... ) are listed in the appendix.

Command	Examples	Comment
С	c(1,2)	concatenates things
d	dnorm(0)	density of a distribution.
dim	dim(X)	dimension of a matrix
function	<pre>rtnew &lt;- function(N,n=2) { rt(N,n) }</pre>	Define a new function
matrix	<pre>matrix(1:4,ncol=2)</pre>	converts to a matrix
par	<pre>par(mfrow=c(2,1)), par(op)</pre>	splits graphical output
q	qnorm(0.95)	the quantile of a distribution.
r	<pre>rnorm(100)</pre>	random numbers from distributions.
rep	rep(2,100)	repeat numbers
seq	seq(1,10,by=0.1)	sequences of numbers
t	t(X)	transpose of a matrix
%*%	A %*% t(X)	matrix multiplication
N.C. (1)	1.6	

Mathematical functions

sin, cos, sqrt, exp, log

## A.1 Distributions

(-)Distribution	S-Name	Parameters
Beta	beta	shape1, shape2, ncp= 0
Binomial	binom	size, prob
Cauchy	cauchy	location= 0, scale= 1
$\chi^2$	chisq	df, ncp= 0
Exponential	exp	rate= 1
F	f	df1, df2 (ncp= 0)
Gamma	gamma	shape, rate= 1
Geometrische	geom	prob
Hypergeometrische	hyper	m, n, k
Log-Normal	lnorm	meanlog= 0, sdlog= 1
Logistische	logis	location= 0, scale= 1
Multinomial	multinom	size, prob
Multivariate Normal	mvnorm	<pre>mean= rep(0,d), sigma=</pre>
(Im package mvtnorm)		diag(d) (with $d = \text{Dimension}$ )
Multivariate t	mtnorm	(complicated; nur $p$ , $q$ und
(Im package mvtnorm)		r)
Negative Binomial	nbinom	size, prob
Normal	norm	mean= 0, sd= 1
Poisson	pois	lambda
Wilcoxon's signed- sum of ranks	signrank	n
Students $t$	t	df, ncp= 0
Uniforme	unif	min= 0, max= 1
Weibull	weibull	shape, scale= 1
Wilcoxon's sum of ranks	wilcox	m, n

We will meet further multivariate distributions in the  $\tt QRMlib$