



# Stochastic Filtering (SS2016) Exercise Sheet 1

Lecture and Exercises: JProf. Dr. Philipp Harms  
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## 1.1. Measures

Let  $(\mathbb{X}, \mathcal{X})$  be a measurable space.

- Give the definitions of the set  $\mathcal{M}(\mathbb{X})$  of  $\sigma$ -finite measures and the subset  $\mathcal{P}(\mathbb{X})$  of probability measures.
- The spaces  $\mathcal{M}(\mathbb{X})$  and  $\mathcal{P}(\mathbb{X})$  are endowed with the  $\sigma$ -algebra generated by the mappings  $\pi_A : \mu \mapsto \mu(A)$ ,  $A \in \mathcal{X}$ . Give the definition of this  $\sigma$ -algebra and show that  $\mathcal{P}(\mathbb{X})$  is a measurable subset of  $\mathcal{M}(\mathbb{X})$ .
- Show that the mappings  $\pi_f : \mu \mapsto \int f d\mu$ , where  $f$  runs through the set of bounded measurable functions on  $\mathbb{X}$ , generate the same  $\sigma$ -algebra.

## 1.2. Kernels

Fix two measurable spaces  $(\mathbb{X}, \mathcal{X})$  and  $(\mathbb{Y}, \mathcal{Y})$ .

- Give the definitions of kernels and probability kernels from  $\mathbb{X}$  to  $\mathbb{Y}$ .
- Show that the mapping  $\delta : \mathbb{X} \times \mathcal{Y} \rightarrow [0, 1]$ ,  $(x, A) \mapsto \mathbf{1}_A(f(x))$  is a probability kernel from  $\mathbb{X}$  to  $\mathbb{Y}$  iff  $f : \mathbb{X} \rightarrow \mathbb{Y}$  is measurable.
- Show that  $P : \mathbb{X} \times \mathcal{Y} \rightarrow [0, 1]$  is a probability kernel from  $\mathbb{X}$  to  $\mathbb{Y}$  iff  $P : \mathbb{X} \rightarrow \mathcal{P}(\mathbb{Y})$  is measurable.



### 1.3. Conditioning

Let  $X$  and  $Y$  be random variables on a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  with values in measurable spaces  $(\mathbb{X}, \mathcal{X})$  and  $(\mathbb{Y}, \mathcal{Y})$ . Moreover, let  $\mathcal{G}$  be a  $\sigma$ -algebra contained in  $\mathcal{F}$ .

- What are the definitions of the regular conditional probabilities  $P_{X|\mathcal{G}}$  and  $P_{X|Y}$ ?
- Are  $\mathbb{P}[X \in \cdot | Y]$  and  $P_{X|Y}(Y, \cdot)$  random probability measures, i.e., probability kernels on  $(\Omega, \mathcal{F})$ ? Which properties need to be verified?
- Show that  $P_{X|\sigma(Y)}(\omega, A) = P_{X|Y}(Y(\omega), A)$  holds identically.

### 1.4. Bayes' formula

Let  $X$  and  $Y$  be random variables with values in measurable spaces  $(\mathbb{X}, \mathcal{X})$  and  $(\mathbb{Y}, \mathcal{Y})$ , respectively. Assume that the law of  $(X, Y)$  can be written in the form  $\Lambda(x, y)\mu_X(dx)\mu_Y(dy)$  for some non-negative measurable function  $\Lambda : \mathbb{X} \times \mathbb{Y} \rightarrow \mathbb{R}$  and some probability measures  $\mu_X \in \mathcal{P}(\mathbb{X})$  and  $\mu_Y \in \mathcal{P}(\mathbb{Y})$ .

- Show that the following is a regular conditional probability of  $X$  given  $Y$ :

$$P_{X|Y}(y, A) = \frac{\int_A \Lambda(x, y)\mu_X(dx)}{\int \Lambda(x, y)\mu_X(dx)}$$

(In the expression above, the fraction is set to zero if the denominator vanishes.)

- Use a) to calculate the regular conditional probability of  $X$  given  $Y$  if  $(X, Y)$  is multivariate Gaussian.

Hint: the solution is  $P_{X|Y}(y, dx) \sim \mathcal{N}(\hat{X}, \hat{\Sigma})$  with

$$\begin{aligned}\hat{X} &= \mathbb{E}[X] + \text{Cov}(X, Y) \text{Var}(Y)^{-1}(y - \mathbb{E}[Y]), \\ \hat{\Sigma} &= \text{Var}(X) - \text{Cov}(X, Y) \text{Var}(Y)^{-1} \text{Cov}(Y, X),\end{aligned}$$

where  $\text{Var}(Y)^{-1}$  is the generalized inverse of the (co-)variance matrix of  $Y$ .



## 1.5. Hidden Markov Models

Let  $(X, Y)$  be a Markov process. Show that the following statements are equivalent:

- The transition kernel of  $(X, Y)$  is of the form  $P(x, dx')K(x', dy')$ .
- $X$  is Markov in the filtration generated by  $(X, Y)$ , and  $Y_{k+1}$  is independent of  $(X_k, Y_k)$  conditional on  $X_{k+1}$ , for each  $k \in \mathbb{N}$ .
- $X_{k+1}$  is independent of  $Y_k$  conditional on  $X_k$ , and  $Y_{k+1}$  is independent of  $(X_k, Y_k)$  conditional on  $X_{k+1}$ , for each  $k \in \mathbb{N}$ .

## 1.6. Hidden Markov Models

- Show that the process  $(X, Y)$  defined by

$$X_{k+1} = f(X_k, \alpha_k), \quad Y_{k+1} = g(X_{k+1}, \beta_k), \quad k = 0, 1, 2, \dots$$

is a Hidden Markov Model, where  $f : \mathbb{X} \times [0, 1] \rightarrow \mathbb{X}$  and  $g : \mathbb{X} \times [0, 1] \rightarrow \mathbb{Y}$  are measurable functions, and where  $(\alpha_k)_{k \in \mathbb{N}}$  and  $(\beta_k)_{k \in \mathbb{N}}$  are independent sequences of i.i.d.  $[0, 1]$ -valued random variables.

- Conversely, show that any Hidden Markov Model is of this form if  $\mathbb{X}$  and  $\mathbb{Y}$  are Borel spaces.

Hint. You may use [1, Theorem 6.10] and the discussions preceding this theorem.

## References

- [1] Olav Kallenberg. *Foundations of modern probability*. 2nd ed. Springer Verlag, New York, 2002.